# Modal Sound Field Decomposition Applicable for a Limited Range of Directions 

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## Introduction

The decomposition of spatial sound scenes using spherical microphone arrays is usually based on spherical harmonics. However, the decomposition in spherical harmonics requires a distribution of microphones covering all directions, even if all sources are not all around. For a restricted range of directions the spherical harmonics can be orthogonalized, yielding the spherical Slepian functions. These are well-suited to interpolate data on a partial spherical domain. However, they introduce large errors when extrapolating sound fields with sources outside the restricted range. A different set of orthogonal functions is obtained by solving the Helmholtz equation with an angular boundary condition, e.g. a directional range delimited by an infinite cone that acoustically excludes sources outside. This article discusses the characteristics of the corresponding spherical cap/segment harmonics compared to the spherical harmonics and Slepian functions applied to holographic sound field extrapolation.

## Modal sound field decomposition

The Helmholtz equation in spherical coordinates ${ }^{1}$ is expressed by $\Delta p(r \boldsymbol{\theta})-k^{2} p(r \boldsymbol{\theta})=0$, where $\Delta$ is the Laplace operator, $p(r \boldsymbol{\theta})$ is the sound pressure, and $k$ is the wave number. Modal sound field decomposition including all directions is based on the solution of the Helmholtz equation. The angular solutions are usually combined and called spherical harmonics $Y_{n}^{m}(\boldsymbol{\theta})=N_{n}^{|m|} P_{n}^{|m|}(\cos \vartheta) \begin{cases}\cos (m \varphi), & \text { for } m \geq 0 \\ \sin (m \varphi), & \text { for } m<0\end{cases}$
of order $n$ and degree $m ; \mathrm{P}_{n}^{|m|}$ denotes the associated Legendre functions, and $N_{n}^{|m|}$ is a scalar normalization term.

A compact spherical microphone array captures the sound pressure distribution on a spherical surface of radius $r_{M}$, which can be expressed by a spherical

[^0]harmonics expansion
\[

$$
\begin{equation*}
p\left(\boldsymbol{r}_{M}\right)=\sum_{n=0}^{\infty} \sum_{m=-n}^{n} Y_{n}^{m}(\boldsymbol{\theta}) \psi_{n m} . \tag{1}
\end{equation*}
$$

\]

The expansion coefficients are obtained by $\psi_{n m}=$ $\int_{\mathbb{S}^{2}} Y_{n}^{m}(\boldsymbol{\theta}) p\left(\boldsymbol{r}_{M}\right) d \boldsymbol{\theta}$, where $\mathbb{S}^{2}$ denotes the unit sphere.

For reproduction, a surrounding spherical loudspeaker array of radius $r_{L}$ is used to approximate the excitation pattern $f(\boldsymbol{\theta})$ of the captured sound scene, cf. [1]. The spherical harmonics expansion of this excitation pattern is $f(\boldsymbol{\theta})=\sum_{n=0}^{\infty} \sum_{m=-n}^{n} Y_{n}^{m}(\boldsymbol{\theta}) \phi_{n m}$.
For a microphone array located on a rigid sphere, the coefficients of the excitation pattern and the pressure distribution are connected by, cf. [2], $\psi_{n m}=$ $\frac{-1}{k r_{M}^{2}} \frac{h_{n}\left(k r_{L}\right)}{h_{n}^{\prime}\left(k r_{M}\right)} \phi_{n m}$. Omitting constant factors, this is accurately approximated at the relevant frequencies as $r_{L}$ is large by, cf. [3, Eq. 10.52.4],

$$
\begin{equation*}
\psi_{n m}=\underbrace{\frac{-i^{n} e^{-i k r_{L}}}{k^{2} h_{n}^{\prime}\left(k r_{M}\right)}}_{w_{n}\left(k r_{M}\right)} \phi_{n m} \tag{2}
\end{equation*}
$$

Up to a critical frequency, high order modes with $n>$ N do not contribute significantly in $w_{n}\left(k r_{M}\right)$. Below this frequency limit the pressure pattern captured by the array is assumed as spatially band-limited, i.e.

$$
\begin{equation*}
p\left(r_{M} \boldsymbol{\theta}\right)=\sum_{n=0}^{\mathrm{N}} \sum_{m=-n}^{n} Y_{n}^{m}(\boldsymbol{\theta}) \psi_{n m} . \tag{3}
\end{equation*}
$$

Aliasing is comprehensively discussed in [4]. For simplicity, absence of aliasing is assumed here

For notational convenience, the double sum in the equation above is expressed by a vector product

$$
\begin{equation*}
p\left(r_{M} \boldsymbol{\theta}\right)=\boldsymbol{y}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) \boldsymbol{\psi}_{\mathrm{N}} . \tag{4}
\end{equation*}
$$

where $\boldsymbol{y}_{\mathrm{N}}(\boldsymbol{\theta}):=\left[Y_{n}^{m}(\boldsymbol{\theta})\right]_{q=1 \ldots(\mathrm{~N}+1)^{2}}$ and
$\psi_{\mathrm{N}}:=\left[\psi_{n}^{m}\right]_{q=1 \ldots(\mathrm{~N}+1)^{2}}$ with the linear index $q:=n^{2}+n+m+1$. Eq.(2) is expressed by

$$
\begin{equation*}
\boldsymbol{\psi}_{\mathrm{N}}=\operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \boldsymbol{\phi}_{\mathrm{N}}, \tag{5}
\end{equation*}
$$

with $\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)=[w_{0}\left(k r_{M}\right), \ldots, \overbrace{w_{\mathrm{N}}\left(k r_{M}\right), \ldots, w_{\mathrm{N}}\left(k r_{M}\right)}^{2 \mathrm{~N}+1}]$ and $\phi_{\mathrm{N}}:=\left[\phi_{n}^{m}\right]_{q=1 \ldots(\mathrm{~N}+1)^{2}}$. The pressure pattern expressed in terms of the excitation pattern yields

$$
\begin{equation*}
p\left(r_{M} \boldsymbol{\theta}\right)=\boldsymbol{y}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \boldsymbol{\phi}_{\mathrm{N}} . \tag{6}
\end{equation*}
$$



Figure 1: Magnitude response of $w_{n}^{-1}\left(k r_{M}\right)$ for $n=0 \ldots 6$.


Figure 2: Possible shapes $S^{2} \subset \mathbb{S}^{2}$ for a restriction in $\vartheta$ : (a) spherical cap where $\vartheta \leq \vartheta_{1}$, and (b), and (b) spherical segment where $\vartheta_{1} \leq \vartheta \leq \vartheta_{2}$.

Inverting Eq.(5), the coefficients of the excitation pattern can be calculated from the coefficients of the pressure distribution captured by the array:

$$
\begin{equation*}
\boldsymbol{\phi}_{\mathrm{N}}=\operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\}^{-1} \boldsymbol{\psi}_{\mathrm{N}} \tag{7}
\end{equation*}
$$

The magnitude responses of $w_{n}^{-1}\left(k r_{M}\right)$ for $n=0 \ldots 6$ are depicted in Fig.1.
We are interested in holographic extrapolation for a limited range of directions, especially in a method requiring the same fraction as the surface on which the sound pressure is captured. Let $S^{2} \subset \mathbb{S}^{2}$ denote fractions of the unit sphere delimited only in the zenith angle $\vartheta$. Fig. 2 illustrated the two possible shapes, (a) a spherical cap where $\vartheta \leq \vartheta_{1}$, and (b) a spherical segment where $\vartheta_{1} \leq \vartheta \leq \vartheta_{2}$. The discussion below focuses on two suitable types of orthogonal bases for such fraction and their application to holographic sound field extrapolation.

## Spherical Slepian functions

The spherical Slepian functions, cf. [5], form an orthogonal basis for both, the entire sphere and the restricted directional range. The Slepian functions $\boldsymbol{v}_{\mathrm{N}}$ span the same function space as the spherical harmonics and they are related by a transformation matrix $\boldsymbol{U}$

$$
\begin{equation*}
\boldsymbol{v}_{\mathrm{N}}(\boldsymbol{\theta})=\boldsymbol{U}^{\mathrm{T}} \boldsymbol{y}_{\mathrm{N}}(\boldsymbol{\theta}) \tag{8}
\end{equation*}
$$

whereby $\boldsymbol{U}$ contains the eigenvectors of $\boldsymbol{G}$, cf. [5], the Gram-matrix $\boldsymbol{G}$ of the spherical harmonics up to order

##  <br>  <br> 

Figure 3: Spherical Slepian functions for a spherical segment with $\vartheta_{1}=60^{\circ}, \vartheta_{2}=120^{\circ}$, spatially band-limited with $n \leq 6$, and a threshold $\sigma=0.9$.
$n<\mathrm{N}$ on $S^{2}$

$$
\begin{equation*}
\boldsymbol{G}=\int_{S^{2} \subset \mathbb{S}^{2}} \boldsymbol{y}_{\mathrm{N}}(\boldsymbol{\theta}) \boldsymbol{y}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) d \boldsymbol{\theta}=\boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{U}^{\mathrm{T}} \tag{9}
\end{equation*}
$$

where $\boldsymbol{\Sigma}=\operatorname{diag}\left\{\left[\sigma_{i}\right]_{1 \ldots(\mathrm{~N}+1)^{2}}\right\}$ contains the eigenvalues $\sigma_{1}<\ldots<\sigma_{(\mathrm{N}+1)^{2}}$. On a rotationally symmetric region, the spherical Slepian functions can be determined for each degree $m$ individually.

In contrast to the spherical harmonics, the Slepian functions exhibit an angular energy concentration. Taking a subset of the spherical Slepian functions $\tilde{\boldsymbol{v}}_{\mathrm{N}}(\boldsymbol{\theta})=\left[v_{i}(\boldsymbol{\theta})\right]_{i=1 \ldots \mathrm{M}}, \quad \mathrm{M}<(\mathrm{N}+1)^{2}$, yields the subspace of band limited functions exhibiting energy concentration in the region of interest. The energy concentration is adjusted by a threshold $\sigma$ such that $\frac{\sigma_{i}}{\max \left(\sigma_{i}\right)}>\sigma$. For this subset Eq.(8) reduces to

$$
\begin{equation*}
\tilde{\boldsymbol{v}}_{\mathrm{N}}(\boldsymbol{\theta})=\tilde{\boldsymbol{U}}^{\mathrm{T}} \boldsymbol{y}_{\mathrm{N}}(\boldsymbol{\theta}) \tag{10}
\end{equation*}
$$

where $\tilde{\boldsymbol{U}}$ is the $(\mathrm{N}+1)^{2} \times \mathrm{M}$ part of the transformation matrix, $\boldsymbol{U}=\left[\tilde{\boldsymbol{U}}, \tilde{\boldsymbol{U}}_{\perp}\right]$. The spherical Slepian functions for a spherical segment up to order $\mathrm{N}=6$ are depicted in Fig. 3 .
Decomposing the captured pressure pattern on $S^{2}$ terms of this subset of spherical Slepian functions yields

$$
\begin{equation*}
\tilde{\boldsymbol{\psi}}_{\mathrm{N}}=\tilde{\boldsymbol{\Sigma}}^{-1} \int_{S^{2} \subset \mathbb{S}^{2}} \tilde{\boldsymbol{v}}_{\mathrm{N}}(\boldsymbol{\theta}) p\left(r_{M} \boldsymbol{\theta}\right) d \boldsymbol{\theta} \tag{11}
\end{equation*}
$$

whereby $\tilde{\boldsymbol{\Sigma}}=\operatorname{diag}\left\{\left[\sigma_{i}\right]_{1 \ldots \mathrm{M}}\right\}$. The decomposition is numerically stable by choosing $\sigma$ sufficiently large.
Inserting Eq.(10) in the above equation and expressing the sound pressure pattern in terms of the excitation pattern, cf. Eq.(6), yields

$$
\tilde{\boldsymbol{\psi}}_{\mathrm{N}}=\tilde{\boldsymbol{\Sigma}}^{-1} \tilde{\boldsymbol{U}}^{\mathrm{T}} \int_{S^{2} \subset \mathbb{S}^{2}} \boldsymbol{y}_{\mathrm{N}}(\boldsymbol{\theta}) \boldsymbol{y}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) d \boldsymbol{\theta} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \boldsymbol{\phi}_{\mathrm{N}}
$$

Inserting the eigendecomposition of Eq.(9) yields

$$
\begin{equation*}
\tilde{\boldsymbol{\psi}}_{\mathrm{N}}=\underbrace{\tilde{\boldsymbol{\Sigma}}^{-1} \tilde{\boldsymbol{U}}^{\mathrm{T}} \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{U}^{\mathrm{T}}}_{\tilde{\boldsymbol{U}}^{\mathrm{T}}} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \boldsymbol{\phi}_{\mathrm{N}} \tag{12}
\end{equation*}
$$

whereby the simplification results from the orthogonality of $\boldsymbol{U}$, i.e. $\tilde{\boldsymbol{U}}^{\mathrm{T}} \boldsymbol{U}=\left[\boldsymbol{I}_{\mathrm{M} \times \mathrm{M}} \mathbf{0}_{\mathrm{M} \times(\mathrm{N}+1)^{2}-\mathrm{M}}\right]$. If we assume that the excitation pattern is suitably angularly limited by the condition $\tilde{U}_{\perp}^{\mathrm{T}} \boldsymbol{\phi}_{\mathrm{N}}=\mathbf{0}$, the excitation can be expressed by $\phi_{\mathrm{N}}=\tilde{\boldsymbol{U}} \tilde{\phi}_{\mathrm{N}}$; and the propagation relation for the spherical Slepian functions yields

$$
\begin{equation*}
\tilde{\boldsymbol{\psi}}_{\mathrm{N}}=\tilde{\boldsymbol{U}}^{\mathrm{T}} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \tilde{\boldsymbol{U}} \tilde{\boldsymbol{\phi}}_{\mathrm{N}} \tag{13}
\end{equation*}
$$



Figure 4: Magnitude response of $\tilde{w}_{i, j}\left(k r_{M}\right)$ for $n \leq 6$; the corresponding basis functions are depicted in Fig. 3


Figure 5: Energy of the error in the excitation pattern $\tilde{\phi}_{\mathrm{N}, \text { err }}$, cf. Eq.(15), for a plane wave impinging from $\vartheta_{s}$ for an array located on a spherical segment with $\vartheta_{1}=60^{\circ}$, $\vartheta_{2}=120^{\circ}$

The inverse yields the coefficients of the excitation pattern $\tilde{\phi}_{\mathrm{N}}$ from the coefficients of the pressure $\tilde{\psi}$ :

$$
\begin{equation*}
\tilde{\boldsymbol{\phi}}_{\mathrm{N}}=\underbrace{\left[\tilde{\boldsymbol{U}}^{\mathrm{T}} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \tilde{\boldsymbol{U}}\right]^{-1}}_{:=\tilde{W}=\left[\tilde{w}_{i, j}\left(k r_{M}\right)\right]_{M \times M}} \tilde{\boldsymbol{\psi}}_{\mathrm{N}} \tag{14}
\end{equation*}
$$

In contrast to capture on the full sphere, cf. Eq.(7), partial capture and holography requires a frequency dependent matrix inversion when using spherical Slepian functions.
Fig. 4 depicts the magnitude response of $\tilde{w}_{i, j}\left(k r_{M}\right)$, cf. Eq.(14) for Slepian functions on a spherical segment, $n \leq$ N, cf. Fig.3.
An error occurs if the excitation pattern is not fulfilling the condition $\tilde{\boldsymbol{U}}_{\perp}^{\mathrm{T}} \boldsymbol{\phi}_{\mathrm{N}} \neq \mathbf{0}$. Such patterns cause sound pressure patterns captured on $S^{2}$, which are misinterpreted. By subtracting² Eq.(12) from Eq.(13), $\tilde{\boldsymbol{\psi}}_{\mathrm{N}, \text { err }}=\tilde{\boldsymbol{U}}^{\mathrm{T}} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \tilde{\boldsymbol{U}}_{\perp} \tilde{\boldsymbol{U}}_{\perp}^{\mathrm{T}} \boldsymbol{\phi}_{\mathrm{N}}$ and inserting into Eq.(14) defines the erroneous contribution to $\tilde{\phi}_{\mathrm{N}}$

$$
\begin{equation*}
\tilde{\boldsymbol{\phi}}_{\mathrm{N}, \mathrm{err}}=\tilde{\boldsymbol{W}} \tilde{\boldsymbol{U}}^{\mathrm{T}} \operatorname{diag}\left\{\boldsymbol{w}_{\mathrm{N}}\left(k r_{M}\right)\right\} \tilde{\boldsymbol{U}}_{\perp} \tilde{\boldsymbol{U}}_{\perp}^{\mathrm{T}} \boldsymbol{\phi}_{\mathrm{N}} . \tag{15}
\end{equation*}
$$

Fig. 5 shows the energy of $\tilde{\phi}_{\mathrm{N}, \text { err }}$ for a plane wave in dependence of its zenith angle of incidence $\vartheta_{s}$ on an array located on a spherical segment with $\vartheta_{1}=60^{\circ}, \vartheta_{2}=120^{\circ}$.

## Spherical cap/segment harmonics

Imposing sound-hard boundary conditions in $\vartheta$ on the Helmholtz equation restricts the limited range of directions $S^{2} \subset \mathbb{S}^{2}$ to a spherical cap, cf. [6], or segment and yields an orthogonal and complete basis on $S^{2}$.

[^1]

Figure 6: (a) semi-infinite cone and (b) infinite double cone.
The angular solutions of the Helmholtz equation fulfilling such a boundary condition are the spherical cap/segment harmonics
$Y_{\nu_{l}(m)}^{m}(\boldsymbol{\theta})=N_{\nu_{l}(m)}^{|m|} P_{\nu_{l}(m)}^{|m|}(\cos \vartheta)\left\{\begin{array}{l}\sin (m \varphi), \text { for } m<0, \\ \cos (m \varphi), \text { for } m>0,\end{array}\right.$
where $P_{\nu_{l}(m)}^{|m|}=\mathrm{P}_{\nu_{l}(m)}^{|m|}+\alpha_{l}(m) \mathrm{Q}_{\nu_{l}(m)}^{|m|} ; \mathrm{P}_{\nu}^{m}, \mathrm{Q}_{\nu}^{m}$ are the associated Legendre functions of non-integer order $\nu$ and $\alpha$ is a scalar weight depending on the type of boundary condition. An algorithm for computing the associated Legendre functions of non-integer order is given in [7].

Semi-infinite cone. A semi-infinite conical scatterer, cf. Fig.6(a), corresponds to the boundary condition $\left.\frac{\partial p(r \boldsymbol{\theta})}{\partial \vartheta}\right|_{\vartheta=\vartheta_{1}}=0$. As this condition concerns only $\vartheta$ it reduces to

$$
\begin{equation*}
\left.\frac{\partial P_{\nu_{l}(m)}^{|m|}(\cos \vartheta)}{\partial \vartheta}\right|_{\vartheta=\vartheta_{1}}=0 . \tag{17}
\end{equation*}
$$

There is an infinite but discrete set of parameters $\nu_{l}(m)$ and $\alpha_{l}(m), l=1 \ldots \infty$, for which the boundary condition is fulfilled. Restricting the functions to be finite in $S^{2}$, requires $\alpha_{l}(m)$ to be zero as $\left|\mathrm{Q}_{\nu}^{m}(\cos \vartheta)\right| \rightarrow \infty$ for $\vartheta \rightarrow 0$.

The zeros of $f(\nu)=\frac{\partial \mathrm{P}_{\nu}^{|m|}\left(\cos \vartheta_{1}\right)}{\partial \vartheta}$ determine the values of $\nu_{l}(m)$. For this purpose a numerical zero-finding algorithm is used, e.g. MATLAB's fzero (derivatives of Legendre functions can be evaluated using one of their recurrence relations, cf. [3, Eq. 14.10.5]).

Infinite double cone. Similarly, an infinite double conical scatterer, cf. Fig.6(b), corresponds to the boundary conditions $\left.\frac{\partial P_{\nu_{l}(m)}^{|m|}(\cos \vartheta)}{\partial \vartheta}\right|_{\vartheta=\vartheta_{1,2}}=0$, which is equivalent to

$$
\begin{equation*}
\left[\frac{\partial \mathrm{P}_{\nu_{l}(m)}^{|m|}(\cos \vartheta)}{\partial \vartheta}+\alpha_{l}(m) \frac{\partial \mathbb{Q}_{\nu_{l}(m)}^{|m|}(\cos \vartheta)}{\partial \vartheta}\right]_{\vartheta=\vartheta_{1,2}}=0 \tag{18}
\end{equation*}
$$

By evaluating at both boundaries $\alpha$ can be eliminated. The zeros of the remaining expression $f(\nu)=$

# thasodo   

Figure 7: Spherical segment harmonics for a double conical boundary condition $\theta_{1}=60^{\circ}, \theta_{2}=120^{\circ}$, and spatially bandlimited with $\nu_{q} \leq 6$.
$\frac{\partial \mathrm{P}_{\nu}^{|m|}\left(\cos \vartheta_{1}\right)}{\partial \vartheta} \frac{\partial \mathrm{Q}_{\nu}^{|m|}\left(\cos \vartheta_{2}\right)}{\partial \vartheta}-\frac{\partial \mathrm{P}_{\nu}^{|m|}\left(\cos \vartheta_{2}\right)}{\partial \vartheta} \frac{\partial \mathrm{Q}_{\nu}^{|m|}\left(\cos \vartheta_{1}\right)}{\partial \vartheta}$ determine the values of $\nu_{l}(m)$. Based on $\nu_{l}(m)$ the values of $\alpha_{l}(m)$ are determined by Eq.(18).

The spherical segment harmonics for a double cone with $\vartheta_{1}=60^{\circ}, \vartheta_{2}=120^{\circ}$, up to order $\mathrm{N}=6$ are depicted in Fig. 7.

Modal sound field decomposition. On spherical cap/segment $S^{2} \subset \mathbb{S}^{2}$ restricted by the boundary, the spherical cap/segment harmonics are orthonormal, $\int_{S^{2} \subset \mathbb{S}^{2}} Y_{\nu_{l}^{\prime}\left(m^{\prime}\right)}^{m^{\prime}}(\boldsymbol{\theta}) Y_{\nu_{l}(m)}^{m}(\boldsymbol{\theta}) d \boldsymbol{\theta}=\delta_{l l^{\prime}} \delta_{m m^{\prime}}$, and complete, $\int_{S^{2} \subset \mathbb{S}^{2}}\left[f(\boldsymbol{\theta})-\sum_{l=0}^{\infty} \sum_{m=-l}^{l} Y_{\nu_{l}(m)}^{m}(\boldsymbol{\theta}) \hat{\phi}_{l m}\right]^{2} d \boldsymbol{\theta}=0$, where $\hat{\phi}_{l m}=\int_{S^{2} \subset \mathbb{S}^{2}} f(\boldsymbol{\theta}) Y_{\nu_{l}(m)}^{m}(\boldsymbol{\theta}) d \boldsymbol{\theta}$ are the expansion coefficients.

For notational convenience, we introduce the linear index $q \in 1 \ldots \mathrm{Q}$ and $\nu_{q}=\nu_{l}(m)$ with $\nu_{1}<\nu_{2}<\ldots<\nu_{\mathrm{Q}} \leq \mathrm{N}$ and $m_{q}, \psi_{q}$ are the associated degrees and expansion coefficients . This allows to express the spatially band limited pressure pattern by

$$
\begin{equation*}
p\left(r_{M} \boldsymbol{\theta}\right)=\hat{\boldsymbol{y}}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) \hat{\boldsymbol{\psi}}_{\mathrm{N}} \tag{19}
\end{equation*}
$$

where

$$
\hat{\boldsymbol{y}}_{\mathrm{N}}(\boldsymbol{\theta}):=\left[Y_{\nu_{1}}^{0}(\boldsymbol{\theta}), \ldots, Y_{\nu_{\mathrm{Q}}}^{m_{\mathrm{Q}}}(\boldsymbol{\theta})\right]
$$

and
$\hat{\psi}_{\mathrm{N}}:=\left[\hat{\psi}_{1}, \ldots, \hat{\psi}_{\mathrm{Q}}\right]$. The spherical cap/segment harmonics expansion of the corresponding excitation pattern yields

$$
\begin{equation*}
f(\boldsymbol{\theta})=\hat{\boldsymbol{y}}_{\mathrm{N}}^{\mathrm{T}}(\boldsymbol{\theta}) \hat{\boldsymbol{\phi}}_{\mathrm{N}} \tag{20}
\end{equation*}
$$

where $\hat{\phi}_{\mathrm{N}}:=\left[\hat{\phi}_{1}, \ldots, \hat{\phi}_{\mathrm{Q}}\right]$.
An array capturing the spherical cap/segment spectrum of the sound pressure at the radius $r_{M}$ receives

$$
\begin{equation*}
\hat{\boldsymbol{\psi}}_{\mathrm{N}}=\operatorname{diag}\left\{\hat{\boldsymbol{w}}_{\mathrm{N}}\left(k r_{M}\right)\right\} \hat{\boldsymbol{\phi}}_{\mathrm{N}} \tag{21}
\end{equation*}
$$

with $\hat{\boldsymbol{w}}_{\mathrm{N}}\left(k r_{M}\right)=\left[\hat{w}_{0}\left(k r_{M}\right), \ldots, \hat{w}_{\mathrm{Q}}\left(k r_{M}\right)\right]$ and

$$
\begin{equation*}
\hat{w}_{q}\left(k r_{M}\right)=\frac{-i^{\nu_{q}} e^{-i k r_{L}}}{k^{2} h_{\nu_{q}}^{\prime}\left(k r_{M}\right)} \tag{22}
\end{equation*}
$$

The radial propagation terms in the above equation are similar to the spherical case, Eq.(5), with the only difference of a non-integer parameter $\nu_{q}$. As the propagation terms behave similarly, the spatial bandlimitation is motivated by the same reason as for the spherical case.

The coefficients of the excitation pattern can be calculated from $\hat{\psi}_{\mathrm{N}}$ by inverting Eq.(21),

$$
\begin{equation*}
\hat{\boldsymbol{\phi}}_{\mathrm{N}}=\operatorname{diag}\left\{\hat{\boldsymbol{w}}_{\mathrm{N}}\left(k r_{M}\right)\right\}^{-1} \hat{\boldsymbol{\psi}}_{\mathrm{N}} \tag{23}
\end{equation*}
$$



Figure 8: Magnitude response of $w_{q}^{-1}\left(k r_{M}\right)$ for $\nu_{q} \leq 6$; the corresponding basis functions are depicted in Fig. 7

Comparing the above equation with Eq.(7), reveals that the expressions are structurally identical. However band limitation has different consequences in the spherical cap/segment harmonics than in he spherical harmonics. Fig. 8 depicts the magnitude responses of $w_{q}^{-1}(k)$ for a double conical boundary and $\nu_{q} \leq 6$.

## Conclusion and prospects

Modal sound field decomposition and holographic extrapolation are applicable to both, spherical Slepian functions and spherical cap/segment harmonics. However, extrapolating spherical Slepian functions requires a frequency dependent matrix inversion and provokes large errors when sources are located outside the directional range of interest. In contrast, extrapolating spherical cap/segment harmonics is structurally identical to spherical harmonics. Theoretically, the physical boundary excludes sources outside. Extrapolating spherical cap/segment harmonics using conical boundaries of finite extent will be investigated in future work.

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    ${ }^{1}$ Within this article, we define the position vector in terms of spherical coordinates as $\boldsymbol{r}=r \boldsymbol{\theta}$, whereby $r$ is the radial distance and $\boldsymbol{\theta}$ is the direction vector $\boldsymbol{\theta}=[\cos (\varphi) \sin (\vartheta), \sin (\varphi) \sin (\vartheta), \cos (\vartheta)]^{\mathrm{T}}$ with $\varphi$ and $\vartheta$ being the azimuth and zenith angle, respectively.

[^1]:    ${ }^{2}$ Note that $\boldsymbol{I}-\tilde{\boldsymbol{U}} \tilde{\boldsymbol{U}}^{\mathrm{T}}=\tilde{\boldsymbol{U}}_{\perp} \tilde{\boldsymbol{U}}_{\perp}^{\mathrm{T}}$.

